(Z)e

App



Name : Uspo : Lagous : Accest information : Alerke : Furtherse Notice :

BEARCH

Welcome United States Patern and Tradamark Office BROWSE

Results for "(((hybrid)<in>metadata) <and> ((kinematic)<in>metadata))<and> ((simulati...* Your search matched 38 of 1749452 documents.

JE EE YPLORE SUIGE

Educational Courses

A maximum of 100 results are displayed, 25 to a page, sorted by Relevance in Descending order.

Modify Search

Display Former

IEEE/IET

d view selected items



(((hybrid)<in>metadata) <and> ((kinematic)<in>metadata))<and> ((simulation)<in: Search > Check to search only within this results set Citation Citation & Abstract

- Sewah Options View Session History

New Search

IFEE STD.

IERE JNS IEEE Journal or Magazine IET JNU IET Journal or Magazine HEER ONE IEEE Conference Proceeding IET ONE IET Conference Proceeding IEEE Standard

1. Using hybrid simulation for a quadruped standing leap

Wei Hu; Marhelka, D.W.; Krasny, D.P.; Orin, D.E.; Intelligent Control and Automation, 2004 WCICA 2004 Fifth World Congress on

Books

IEEE/IET journals, transactions, letters, magazines, conference proceedings, and standards.

Select All Deselect All

Volume 5. 15-19 June 2004 Page(s):4603 - 4608 Vol.5 AbstractPlus | Full Text: PDF(516 KB) : EEE CMF

Rights and Permissions

Rights and Permissions

2. Hybrid kinematic and dynamic simulation of running machines 1 Wei Hu; Marhetka, D.W.; Orin, D.E.;

> Robotics, IEEE Transactions on Isse also Robotics and Automation, IEEE Transactions on) Volume 21, Issue 3, June 2005 Page(s):490 - 497 Digital Object Identifier 10.1109/TRO.2004.839226

AbstractPlus | References | Full Text; PDF(328 KB) | IEEE INL.

3. A hybrid strategy to solve the forward kinematics problem in parallel manipulators Parikh, P.J.; Lam, S.S.Y.;

> Robotics, IEEE Transactions on [see also Robotics and Automation, IEEE Transactions on] Volume 21, issue 1, Feb 2005 Page(s):18 - 25 Digital Object Identifier 10.1109/TRO.2004.833801

AbstractPlus | Full Text: PDF(560 KB) HEEE JAB.

Rights and Permissions

4. The Tricept robot: dynamics and impedance control F. Caccavale; B. Siciliano; L. Villani;

> Mechatronics, IEEE/ASME Transactions on Volume 8, issue 2, June 2003 Page(s):263 - 268

Digital Object Identifier 10.1109/TMECH.2003.812839 AbstractPlus | References | Full Text; PDF(500 KB) | (8.99 JNs.

Rights and Permissions

Hybrid probabilistic RoadMap - Monte Carlo motion planning for closed chain systems with sphe Li Han

Robotics and Automation, 2004. Proceedings. ICRA 04, 2004 IEEE International Conference on



Page 3 of 4

	13.	Inverse Kinematics for a Point-Foot Quadruped Robot with Dynamic Redundancy Resolution Shkotinik, A. Tedake, R. P. Shkotinik, A. Tedake, R. Shkotinik, R. Sh
		AbstractPos Full Text: PDF(974 KB) HEECONF Rothe and Permissions
	14.	Error Model and Kinematic Calibration of a 5-axis Hybrid Machine Tool. Jam-Woo Kim, Jun-Woo Kim, Chang-Risk Shin: Han-Sung Kim, Jin-Ho Kyung; Young-Ho Ha; SSCE-LGASE; Zook International Janic Conference Oct. 2009 Page(6):3111-3115 Dipliad Dipliad Chieffer (0.1109/SICE 2006.314800
		AbstractPlus Full Text: PDF(4582 KB) + BBB Chif Rights and Permeatice
f	15.	Kinematics Control for a 7-DOF Cable-Driven Anthropomorphic Arm Wehal Chen, Quantu Chen, Janebin Zhang, Shouqian Yu, Indeligent Richote and Systems, 2006 IEEE/RSJ International Conference on Oct. 2009 Pagely) 1850 - 1855 Digital Object Identifier 10.1109/IROS 2006 282119
		AbstractPlus Full Text: PDE(6512 KB) HEEE ONE Rights and Permissions
	16.	A multilevel model for movement rehabilitation in Traumatic Brain Injury (TBI) using Virtual Envil. Wilson, P.H.; Thomas, P.; Shum, D.; Dudworth, J.; Gugliernett, M.; Rudolph, H.; Mumford, N.; Eldridge Virtual Britabili
		AbstractPlus Full Text: PDF(247 KB) IEEE CNF Bights and Permissions
С	17.	Singularity Avoidance in Redundant Robots Using Hybrid Automaton dos Santos, C.H.; Bittencourt, G.; Gwenther, R.; De Perki, E.; Cocketd Apolestands, 2008 IEEE international Conference of Oct. 2009 Page(e); 2854 - 2889 D
		AbstractPus Full Text: PDF(807 KB)
	18.	Hybrid sliding-mode fuzzy neural network tracking control for a wheeled mobile manipulator Mang-Bi Cheng: Ching-Chin Tasik Industrial Technology, ACS, LIGT 2005, IEEE International Conference on 14-17 Dec. 2005 Page(s):944 - 949 Digital Object Meditin Fo. 11 09/IGT 2005 16:00771 AbstractFlus I Full Text PDE(1144 KB) :IEEE Chif Babtas and Permission
	19.	Design, Kinematic Analysis, and Quasi-Steady Control of a Morphic Rolling Disk Biped Climbing
		Shores, B.E.; Minor, M.A.; Bebstuis and Automation, 2005. ICRA 2005, Proceedings of the 2005 IEEE, International, Conference or 18-22 April 2005 Page(s):2721-2726
		AbstractPas Full Text: PDF(472 KB) IEES CNF Fights and Permessions
	20.	Kinematic modelling of multilingered hand's finger gaits as hybrid automation Jijar Xu; Zixiang Li, Toxiang Li, To

AbstractPlus | Full Text: PDF(472 KB) 155 € CNF Rights and Permissions 21. Robust Backstepping Tracking Control Using Hybrid Sliding-Mode Neural Network for a Nonhold with Dual Arms Meng-Bi Cheng; Ching-Chih Tsai; Decision and Control, 2005 and 2005 European Control Conference. CBC-ECC '05, 44th IEEE Confere 12-15 Dec. 2005 Page(s):1964 - 1969 AbstractPlus | Full Text: PDF(3944 KB) IEEE CNF Rights and Permissions 22. Hybrid robust tracking control for a mobile manipulator via sliding-mode neural network Meng-Bi Cheng; Ching-Chih Tsai; Mechatronics, 2005. ICM '05, IEEE International Conference on 10-12 July 2005 Page(s):537 - 542 AbstractPlus | Full Text: PDF(338 KB) IEEE CNF Rights and Permissions 23. UAV optimal path planning using C-C-C class paths for target touring Hong Wong; Kapila, V.; Vaidyanathan, R.; Decision and Control, 2004, CDC, 43rd IEEE Conference on Volume 1, 14-17 Dec. 2004 Page(s):1105 - 1110 Vol.1 AbstractPlus | Full Text: PDF(1920 KB) IEEE ONF Rights and Permissions 24. A hybrid integrity solution for precision landing and guidance Gold, K.L.; Brown, A.K.; Position Location and Navigation Symposium, 2004 PLANS 2004 26-29 April 2004 Page(s):165 - 174 AbstractPlus | Full Text: PDF(616 KB) :EEE CNF Rights and Permissions 25. Motion planning of a bipedal miniature crawling robot in hybrid configuration space V Jizhong Xiao; Ning Xi; Dulimarta, H.; Tummala, R.L.; Intelligent Robots and System, 2002. IEEE/RSJ International Conference on Volume 3, 30 Sept.-5 Oct. 2002 Page(s):2407 - 2412 vol.3 Digital Object Identifier 10.1109/IRDS.2002.1041628 AbstractPlus | Full Text: PDF(569 KB) IEEE CAF Rights and Permissions



Help Contact Us @ Copyright &